## MIT ROCKET TEAM

#### FLIGHT READINESS REVIEW

### Overview

- Mission Updates
- Rocket and Subsystems Updates
- Payload and Subsystems updates
- Full Scale Test Results
- Management Updates

### Purpose and Mission Statement

#### Our Mission:

The MIT Rocket Team aims to develop and test methods of analyzing the causes and effects of fin flutter as it pertains to the flight of high powered rockets.

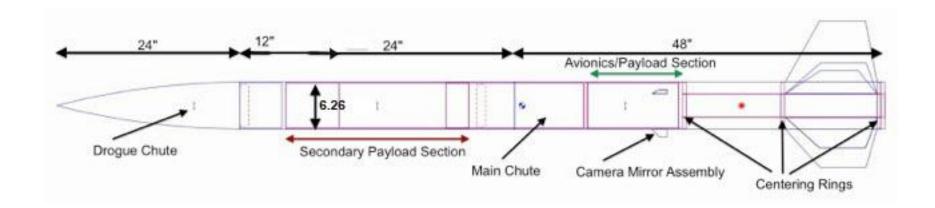
### Mission Requirements

- Launch rocket with 6 fins of different thicknesses, geometry, and materials
  - Analytically demonstrate rocket stability with 6 fins and additionally only the 3 non-fluttering fins.
  - Attach strain gauges to fins to measure predicted versus actual strain
  - Purposely induce flutter or failure in 3 of 6 fins
- Successfully deliver high school outreach payload
- Visually identify flutter effects with high speed camera and custom mirror system
  - Use image post-processing software to accurately track fin movement

### Rocket Overview (1)

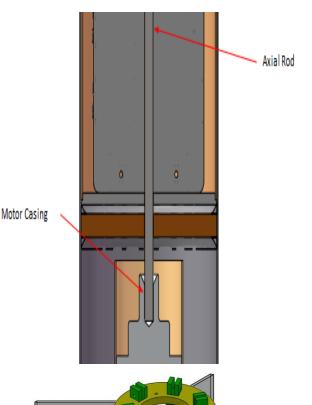
- Requirements:
  - Launch rocket to 5280 ft
  - Induce flutter in 3 test fins
  - Deploy High School Science Payload

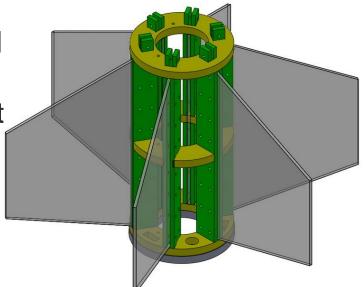
- Final Launch Vehicle Dimensions
  - 9'0" Tall
  - 6" Diameter
  - 42.5 Pound liftoff weight



## Rocket Overview (2)

- Key Design Features
  - Motor retention via threaded rod to recovery eye bolt
  - Fin Retention via custom waterjetted frame
  - Avionics package inside coupler tube above motor
  - Recovery package consisting of dual deployment via Tender Descender with high school payload deployment





### Rocket Airframe and Materials

- Airframe
  - PML 6" Phenolic
  - Carbon fiber: Soller Composites Sleeve
  - Aeropoxy 2032/3660
- Bulkheads & Centering Rings
  - ½" Plywood
  - Wood glued to motor mount tube
- Fins
  - G10/FR4
  - Mechanically attached and removable/ replaceable
- Various
  - Phenolic tubing: motor mount, avionics package
  - Nylon: avionics assembly components
  - Stainless steel: quick links, eye bolts
  - Nomex: chute protectors, deployment bags

### Final Motor Choice

- Rocket Motor Cesaroni L1395
  - 4895N-s impulse more than enough to reach target altitude given mass estimates
  - Proven track record and simple assembly
  - Cheaper and more reliable than Aerotech alternative
- Full-scale Test Motor Cesaroni L1395
  - Will provide nearly identical flight profile to test flutter experiment
- Thrust to Weight Ratio: 8.1:1
- Rail exit velocity: 60ft/sec (assuming 96" of guidance)

### Motor and Flight Profile

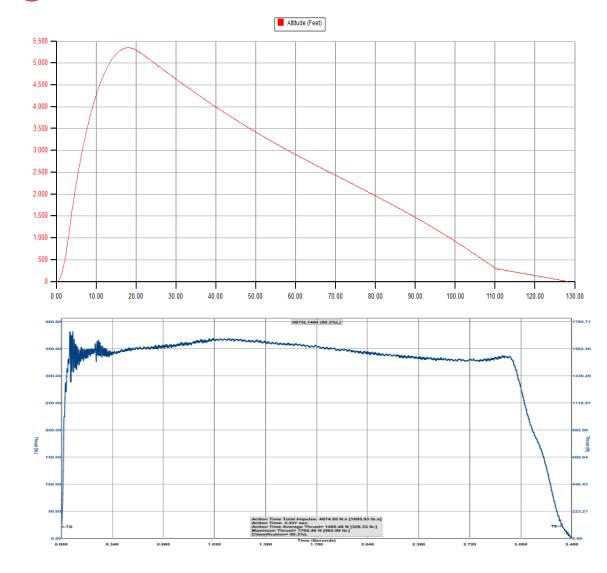
Motor: Cesaroni

L1395

•Ballast Selection:

- Minimize sensitivity
- Adjust for local conditions
- Remain below designated altitude

•Target: 5350 feet



## Static stability margin

- Center of Pressure
  - 92" from nose tip
- Center of Gravity
  - 74" from nose tip at launch
- Stability Margin
  - ~3.0 Calibers



### Vehicle Mass

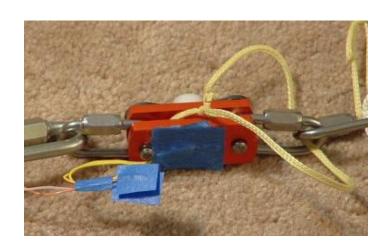
Launch Mass: 42.5 Pounds

Mass margin: ~.5 pounds or 1%

 Rocket has already been built and flown, so mass is very well known

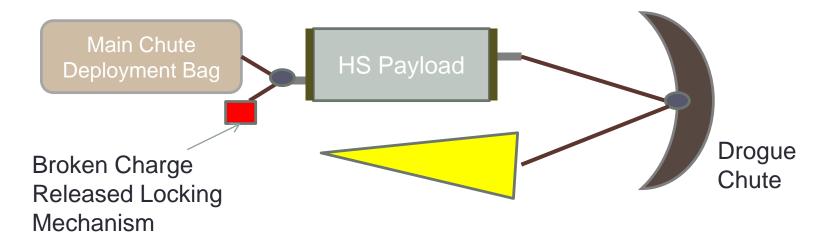
### Rocket Recovery System

- 5 ft drogue parachute
  - Deployment at apogee
  - Shear 2x 2-56 screws
  - 6g black power charge
  - 16' x 1" tubular nylon webbing harness
- 16 ft main parachute
  - Deployment at 300 feet
  - Pulled out by high school payload
  - High school payload released by Tender Descender
  - Deployment Bag used
  - 3.25' x 1" tubular nylon webbing harness



## High School Payload Deployment

- Tube-Stores payload during flight
- Charge released locking mechanism releases sabot at 300 ft
- Chute Bag ensures clean main parachute opening
- Separation of rocket and nose cone prevents parachute entanglement



### Descent Rates and Drift Calculations

Final Descent Rate & Energy					
System Under Drogue	55 ft/s	1670ft-lbf			
Nose/Payload Final Descent Rate	19.1 ft/s	72ft-lbf			
Rocket Body Under Main	13 ft/s	65ft-lbf			
Liberated Fin	<40 ft/s	<9 ft-lbf			

Drift Calculations					
Section Drift	Main Body	Nose cone and payload	Fin 1 (light)	Fin 2 (heavy)	
Descent Time	113 seconds	106 seconds	16 seconds	33 seconds	
Drift at 0mph	0	0	0	0	
5mph	828'	777'	117'	242'	
10mph	1656'	1554'	235'	484'	
15mph	2484'	2331'	352'	726'	
20mph	3312'	3108'	470'	968'	

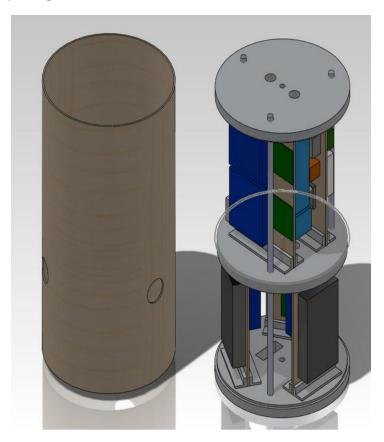
### Vehicle Safety Verification and Testing

- Body tube structural tests
  - Passed on January 15.
- Ejection Charge Tests
  - Passed on January 15-6 grams gently separates nose cone
- Fin drop tests
  - Performed January 20, descent rates of 39 and 28 fps for each fin thickness without streamers
- Avionics Tests
  - Vacuum Chamber
  - Electric match actuation
  - Passed January 14<sup>th</sup> & 15<sup>th</sup>.

### Payload Design Overview

Fin flutter measurement system to quantitatively analyze the fin flutter induced modes in the three test fins

- High-speed Cameras
  - A Cassio Exilim camera for each fin
  - Recording at 480 frames per second
  - Securely mounted in avionics bay
- Software and Simulations
  - Models
    - Rockety Online
    - AeroFimSim 4.0
    - Reinfuth and Smith
    - Rocket Team
  - OpenCV image processing
  - Matlab image processing
  - Matlab strains to deflections converter
- Data (Predicted vs Experimental)
  - Time, velocity, and altitude at which fins experience flutter
  - Fin deflections versus time and velocity



### Payload Design Overview

#### Fin Design

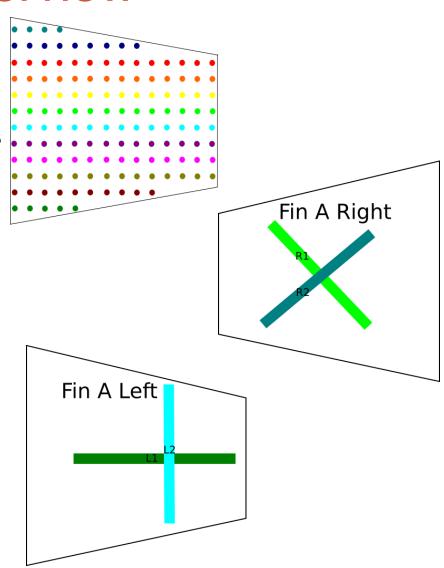
- Colored dot grid pattern
- Pattern printed on sticker which is attached to the fin
- Expected maximum flutter frequency <100Hz</li>

#### Strain Gauges

- 4 on each fin
- 6 inches long
- Data logged at over 1400Hz
- Saved to SD card via Arduino

#### Mirrors

- Mounted on the outside of rocket
- Enables head-on view of each fin



## Payload Integration

- Strain gauges mounted to fins
- Internal electrical connections to avionics bay without tube on
- Tube slid onto avionics bay and fin unit stack and secured with screws

### Interfaces

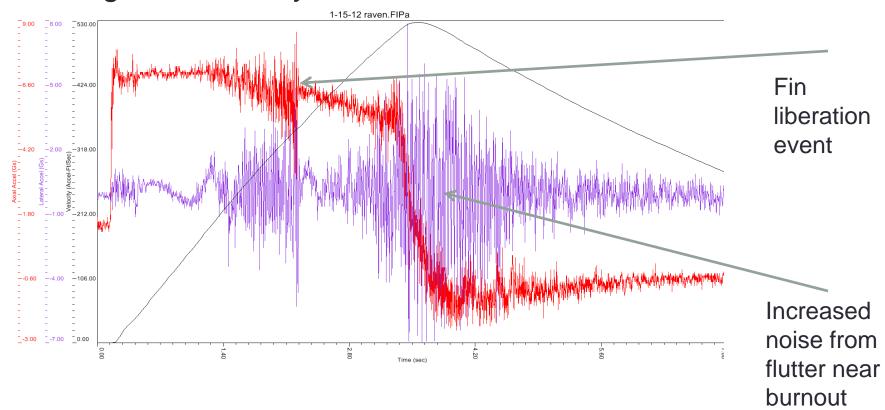
- Launch Rail
- Motor Clips
- Internal connection of avionics to ejection charges and strain gauges with headers
- Solenoid interface to activate cameras prior to launch

#### Full Scale Launch

- January 15 with MDRA outside Price, MD
- L1395
- 44.8 pound liftoff weight
- 15-20mph winds
- 4,890' apogee
- Test fins of same design as main fins, thicknesses of 1/32", 1/16" and 1/8" flown
- 1/32" fin failed at 2.3 seconds. 1/16" fin clearly fluttering.
- Streamer recovery not viable-free fin recovery slow enough

#### Full Scale Accelerometer Data

- Fin liberation event seen at 2.3 seconds.
- Noise from fin flutter clearly increases near burnout
- Integrated velocity and acceleration data not valid



### Full Scale Launch

- March 24 with MMMS near Berwick, MN
- K1440
- 42.5 pound liftoff weight





## Staged Recovery System Tests

- Altimeters and charges checked out prior to flight
- Full scale flight 1 recovery 100% successful









#### Launch vehicle verification and test plan overview and status

- Subsystem Tests
  - Ejection Charges
  - Avionics
  - Recovery
    - Fin
    - Vehicle
- 3 Full Scale Test Launches
  - <u>1/15 at MDRA</u>
  - 2/18 at CRMRC
  - 3/25 at MMMs
- Final Flight
  - 4/7 at MMMS
- Competition Launch
  - 4/21 Huntsville, AL

# QUESTIONS?