

### Exercises on Cramer's rule, inverse matrix, and volume

**Problem 20.1:** (5.3 #8. *Introduction to Linear Algebra: Strang*) Suppose

$$A = \begin{bmatrix} 1 & 1 & 4 \\ 1 & 2 & 2 \\ 1 & 2 & 5 \end{bmatrix}.$$

Find its cofactor matrix  $C$  and multiply  $AC^T$  to find  $\det(A)$ .

$$C = \begin{bmatrix} 6 & -3 & 0 \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \text{ and } AC^T = \text{_____}.$$

If you change  $a_{1,3} = 4$  to 100, why is  $\det(A)$  unchanged?

**Solution:** We fill in the cofactor matrix  $C$  and then multiply to obtain  $AC^T$ :

$$C = \begin{bmatrix} 6 & -3 & 0 \\ 3 & 1 & -1 \\ -6 & 2 & 1 \end{bmatrix}$$

and

$$AC^T = \begin{bmatrix} 1 & 1 & 4 \\ 1 & 2 & 2 \\ 1 & 2 & 5 \end{bmatrix} \begin{bmatrix} 6 & 3 & -6 \\ -3 & 1 & 2 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} = 3I.$$

Since  $AC^T = \det(A)I$ , we have  $\det(A) = 3$ . If 4 is changed to 100,  $\det(A)$  is unchanged because the cofactor of that entry is 0, and thus its value does not contribute to the determinant.

**Problem 20.2:** (5.3 #28.) Spherical coordinates  $\rho, \phi, \theta$  satisfy

$$x = \rho \sin \phi \cos \theta, \quad y = \rho \sin \phi \sin \theta \text{ and } z = \rho \cos \phi.$$

Find the three by three matrix of partial derivatives:

$$\begin{bmatrix} \partial x / \partial \rho & \partial x / \partial \phi & \partial x / \partial \theta \\ \partial y / \partial \rho & \partial y / \partial \phi & \partial y / \partial \theta \\ \partial z / \partial \rho & \partial z / \partial \phi & \partial z / \partial \theta \end{bmatrix}.$$

Simplify its determinant to  $J = \rho^2 \sin \phi$ . In spherical coordinates,

$$dV = \rho^2 \sin \phi d\rho d\phi d\theta$$

is the volume of an infinitesimal "coordinate box."

**Solution:** The rows are formed by the partials of  $x, y,$  and  $z$  with respect to  $\rho, \phi,$  and  $\theta$ :

$$\begin{bmatrix} \sin \phi \cos \theta & \rho \cos \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \cos \phi \sin \theta & \rho \sin \phi \cos \theta \\ \cos \phi & -\rho \sin \phi & 0 \end{bmatrix}.$$

Expanding its determinant  $J$  along the bottom row, we get:

$$\begin{aligned} J &= \cos \phi \begin{bmatrix} \rho \cos \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \rho \cos \phi \sin \theta & \rho \sin \phi \cos \theta \end{bmatrix} \\ &\quad - (-\rho \sin \phi) \begin{bmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta \end{bmatrix} + 0 \\ &= \cos \phi (\rho^2 \cos \phi \sin \phi \cos^2 \theta + \rho^2 \cos \phi \sin \phi \sin^2 \theta) \\ &\quad + \rho \sin \phi (\rho \sin^2 \phi \cos^2 \theta + \rho \sin^2 \phi \sin^2 \theta) \\ &= \cos \phi (\rho^2 \cos \phi \sin \phi (\cos^2 \theta + \sin^2 \theta)) + \rho \sin \phi (\rho \sin^2 \phi (\cos^2 \theta + \sin^2 \theta)) \\ &= \cos \phi (\rho^2 \cos \phi \sin \phi) + \rho^2 \sin^3 \phi \\ &= \rho^2 \sin \phi (\cos^2 \phi + \sin^2 \phi) \\ J &= \rho^2 \sin \phi. \end{aligned}$$